

# 國立臺北科技大學

## 九十四學年度機電整合研究所入學考試

### 自動控制試題

填 准 考 證 號 碼

第一頁 共二頁

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#### 注意事項：

1. 本試題共五題，配分共 100 分。
2. 請按順序標明題號作答，不必抄題。
3. 全部答案均須答在答案卷之答案欄內，否則不予計分。

1. 20% For the mechanical system shown in Figure 1-1, in which  $m = 1, b = 2, k = 2$ ,
  - A. Consider the motion of the massless cart  $u(t)$  as the input, and the motion of the mass  $m, y(t)$ , as the output with all initial conditions are zero. Derive the transfer function of this system.
  - B. If the input function  $u(t)$  is drawn as shown in Figure 1-2, what is the output function  $y(t)$ ?

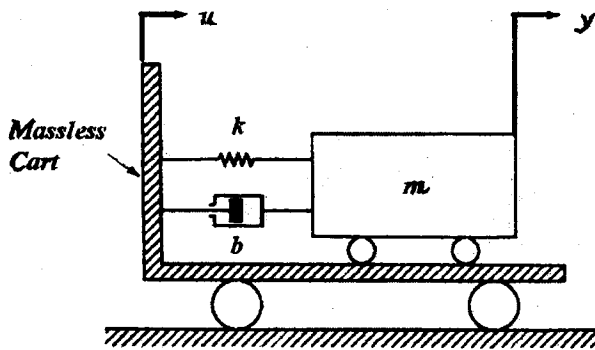


Figure 1-1

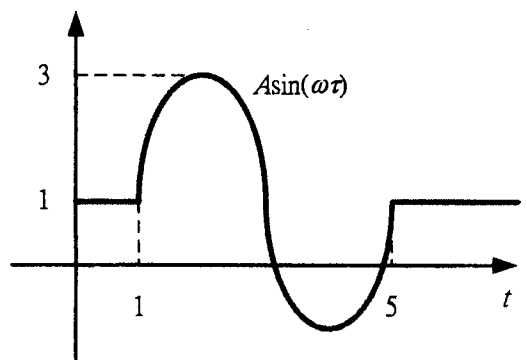


Figure 1-2

2. 20% A system as shown in Figure 2 is required to have the following specifications
- Percentage Overshoot  $< 5\%$
  - Settling Time  $< 2\text{sec}$
- Draw the permissible area on the  $s$ -plane, which satisfies the above requirements.
  - Determine the value  $K$ ,  $p$  and locations of the poles such that one pole,  $s_1$ , has minimum undamped natural frequency  $\omega_n$  and another,  $s_2$ , whose magnitude is 4 times of  $s_1$
  - Draw the Bode diagrams of the loop transfer function selected in B and determine the Gain Margin and Phase Margin.

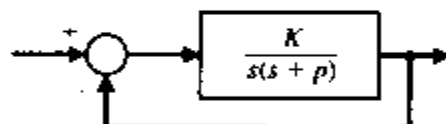
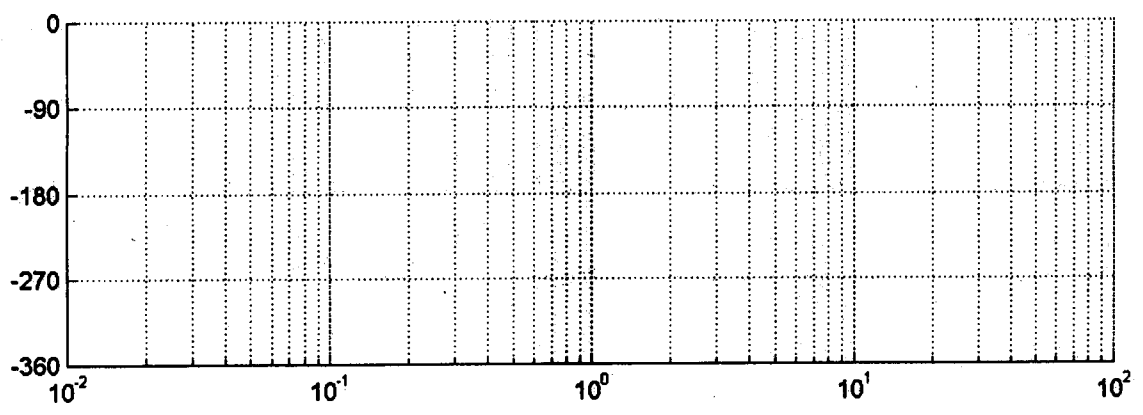
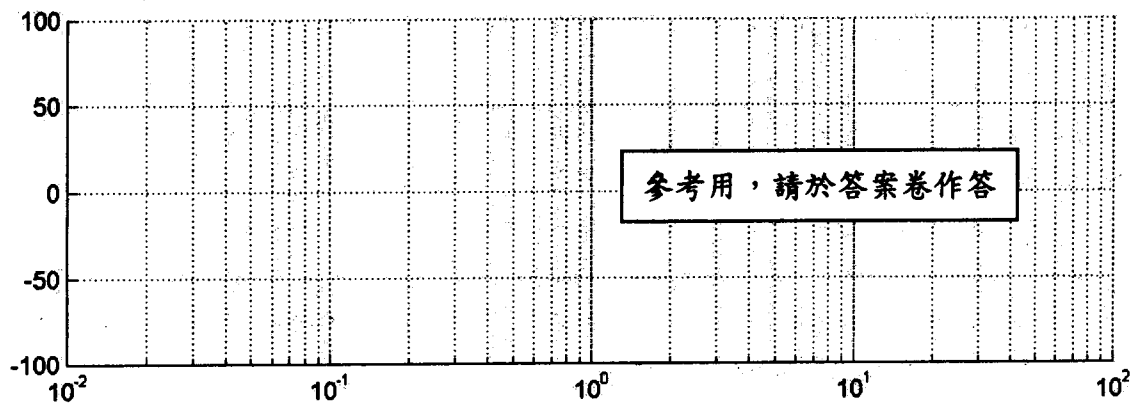


Figure 2

- 20% For the system shown in Figure 2, if the parameters is chosen as  $K = 4$ ,  $p = 2$ , design a compensator so that the static velocity error constant  $K_v$  is  $20/\text{sec}$ , the phase margin is at least  $50^\circ$ , and the gain margin is at least  $10\text{ dB}$ .
- 20% A continuous control plant  $G_p(s)$  is discretized with sampling time  $T = 1$  and zero-order-hold and has an overall discrete transfer function,

$$G(z) = \frac{0.3678z + 0.2644}{(z-1)(z-0.3678)}$$

- Determine the stability of this discrete system.
- Determine the transfer function of the continuous plant  $G_p(s)$ .
- If the system hardware is upgraded such that the sampling time is shorten as  $T = 0.1$ , determine the new corresponding discrete transfer function.



5. 20% For a minimum phase plant  $G(s)$  as shown by the Nichols chart in Figure 3,

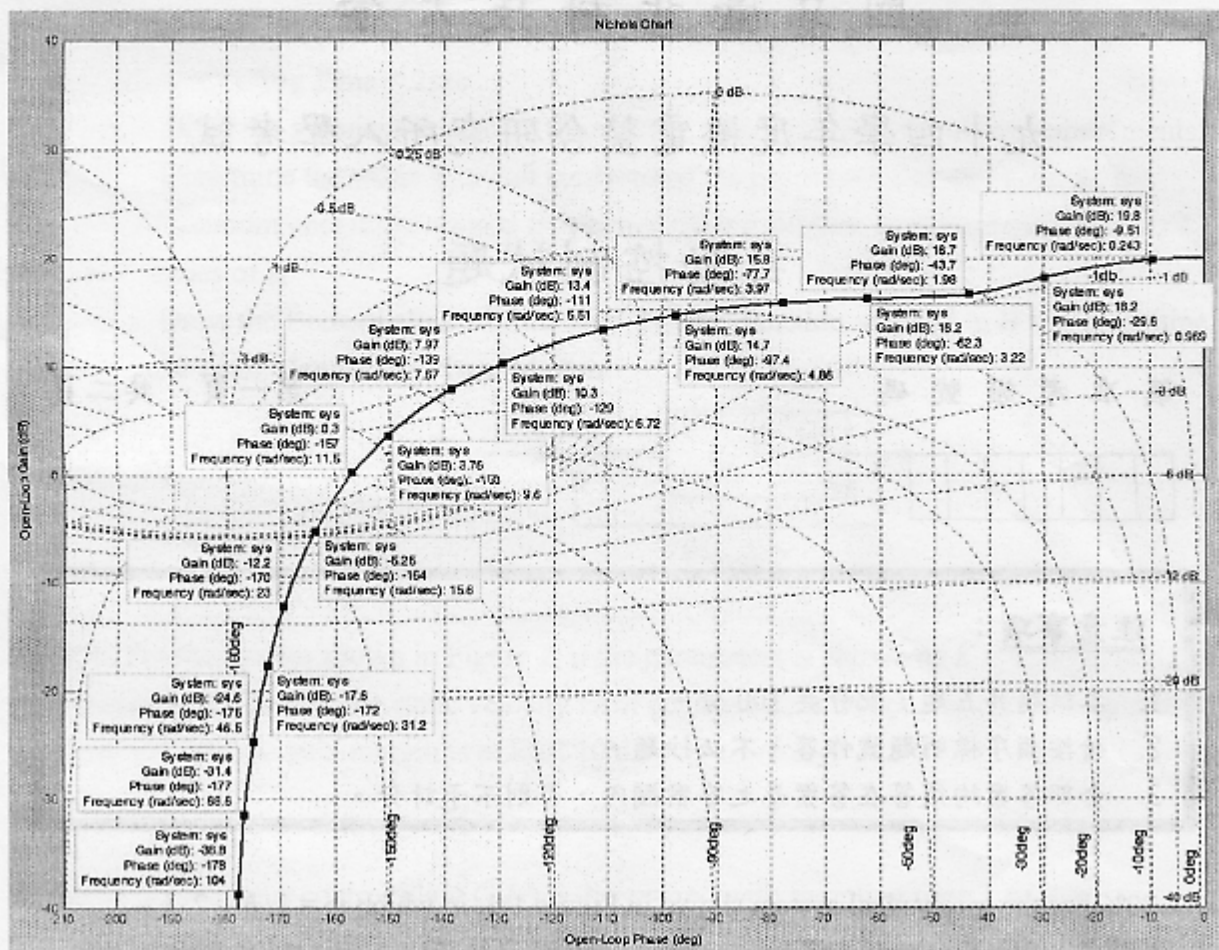


Figure 3

- Determine the Gain and Phase Margin of this plant  $G(s)$ .
- Determine the transfer function of the plant  $G(s)$  shown.
- If a unity negative feedback gain  $H = 1$  is applied to this plant, what is the Gain and Phase margins of this feedback system.
- For the unity negative feedback system, determine if there is any pole of which the real part is between -2 and -4.

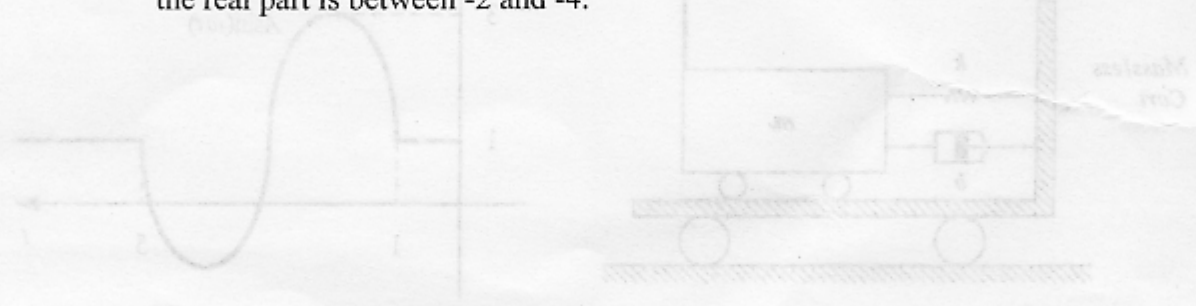


Figure 3

Figure 1-1